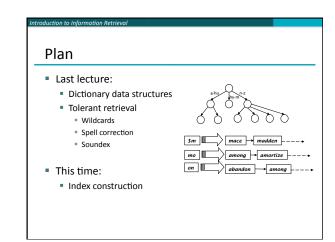
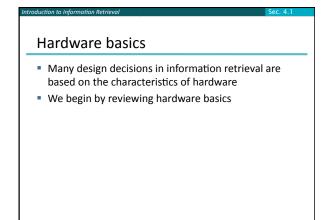
Introduction to Information Retrieval CS276: Information Retrieval and Web Search Pandu Nayak and Prabhakar Raghavan Lecture 4: Index Construction

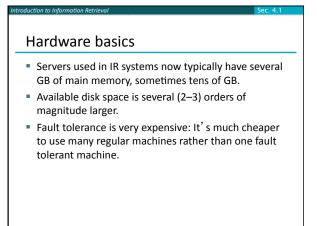


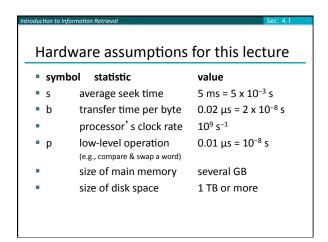
Index construction How do we construct an index? What strategies can we use with limited main

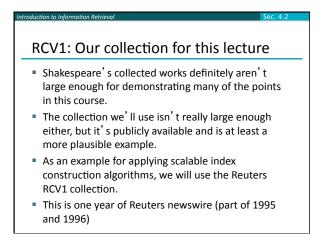
memory?

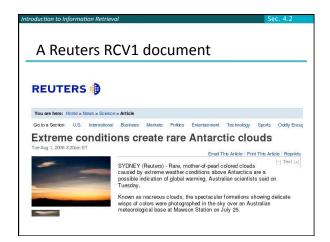


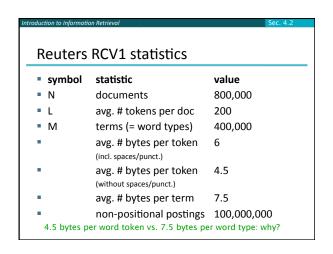
Hardware basics Access to data in memory is *much* faster than access to data on disk. Disk seeks: No data is transferred from disk while the disk head is being positioned. Therefore: Transferring one large chunk of data from disk to memory is faster than transferring many small chunks. Disk I/O is block-based: Reading and writing of entire blocks (as opposed to smaller chunks). Block sizes: 8KB to 256 KB.

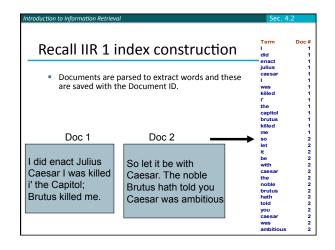


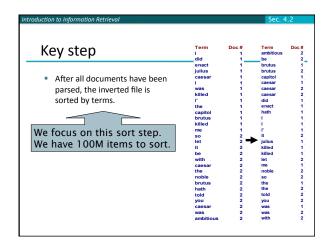










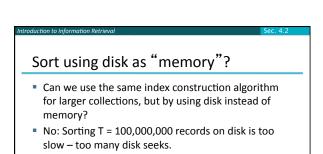


Scaling index construction In-memory index construction does not scale

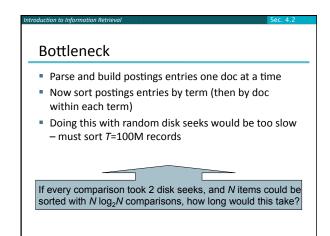
- Can't stuff entire collection into memory, sort, then write back
- How can we construct an index for very large collections?
- Taking into account the hardware constraints we just learned about . . .
- Memory, disk, speed, etc.

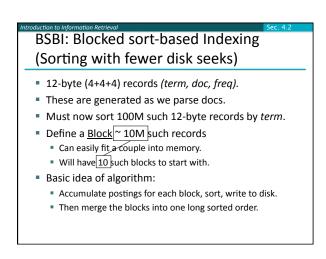
Sort-based index construction

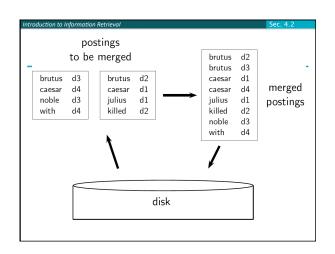
- As we build the index, we parse docs one at a time.
 - While building the index, we cannot easily exploit compression tricks (you can, but much more complex)
- The final postings for any term are incomplete until the end.
- At 12 bytes per non-positional postings entry (term, doc, freq), demands a lot of space for large collections.
- T = 100,000,000 in the case of RCV1
 - So ... we can do this in memory in 2009, but typical collections are much larger. E.g., the New York Times provides an index of >150 years of newswire
- Thus: We need to store intermediate results on disk.



• We need an external sorting algorithm.

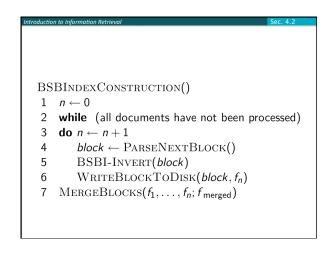


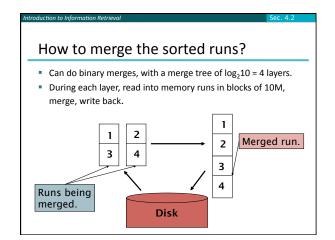


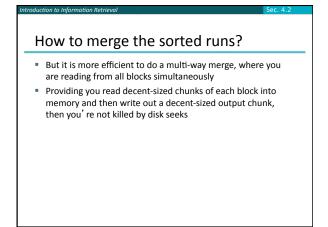


Sorting 10 blocks of 10M records First, read each block and sort within: Quicksort takes 2N In N expected steps In our case 2 x (10M In 10M) steps • Exercise: estimate total time to read each block from disk and and quicksort it. • 10 times this estimate – gives us 10 sorted <u>runs</u> of 10M records each. Done straightforwardly, need 2 copies of data on disk

But can optimize this







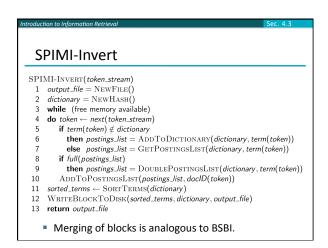
Remaining problem with sort-based algorithm

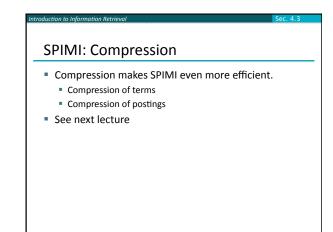
- Our assumption was: we can keep the dictionary in memory.
- We need the dictionary (which grows dynamically) in order to implement a term to termID mapping.
- Actually, we could work with term, docID postings instead of termID, docID postings . . .
- . . . but then intermediate files become very large. (We would end up with a scalable, but very slow index construction method.)

Single-pass in-memory indexing Key idea 1: Generate separate dictionaries for each

SPIMI:

- block no need to maintain term-termID mapping across blocks.
- Key idea 2: Don't sort. Accumulate postings in postings lists as they occur.
- With these two ideas we can generate a complete inverted index for each block.
- These separate indexes can then be merged into one big index.





Distributed indexing • For web-scale indexing (don't try this at home!):

- must use a distributed computing cluster
- Individual machines are fault-prone Can unpredictably slow down or fail
- How do we exploit such a pool of machines?

Web search engine data centers Web search data centers (Google, Bing, Baidu) mainly contain commodity machines. Data centers are distributed around the world. Estimate: Google ~1 million servers, 3 million processors/cores (Gartner 2007)

Massive data centers If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of

- the system?
- Answer: 63%
- Exercise: Calculate the number of servers failing per minute for an installation of 1 million servers.

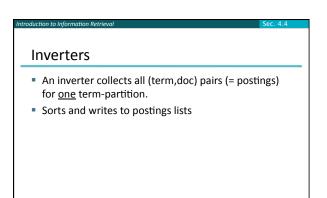
Distributed indexing Maintain a master machine directing the indexing job - considered "safe". Break up indexing into sets of (parallel) tasks. Master machine assigns each task to an idle machine from a pool.

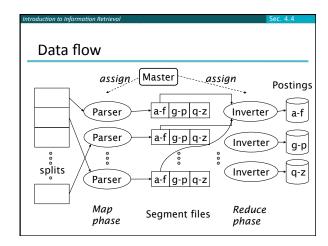
Parallel tasks We will use two sets of parallel tasks

- Parsers
- Inverters
- Break the input document collection into splits
- Each split is a subset of documents (corresponding to blocks in BSBI/SPIMI)

Parsers Master assigns a split to an idle parser machine Parser reads a document at a time and emits (term, doc) pairs Parser writes pairs into j partitions Each partition is for a range of terms' first letters (e.g., a-f, g-p, q-z) – here j = 3.

Now to complete the index inversion





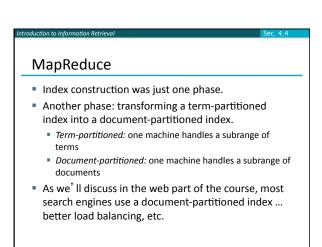
MapReduce

The index construction algorithm we just described is an instance of MapReduce.

MapReduce (Dean and Ghemawat 2004) is a robust and conceptually simple framework for distributed computing ...

... without having to write code for the distribution part.

They describe the Google indexing system (ca. 2002) as consisting of a number of phases, each implemented in MapReduce.



Schema for index construction in MapReduce

- Schema of map and reduce functions
- map: input \rightarrow list(k, v) reduce: (k,list(v)) \rightarrow output
- Instantiation of the schema for index construction
- map: collection → list(termID, docID)
- reduce: (<termID1, list(docID)>, <termID2, list(docID)>, ...) →
 (postings list1, postings list2, ...)

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Example for index construction

- Map
- d1 : C came, C c' ed.
- d2 : C died. →
- <C,d1>, <came,d1>, <C,d1>, <c' ed, d1>, <C, d2>, <died,d2>
- Reduce:
- (<C,(d1,d2,d1)>, <died,(d2)>, <came,(d1)>, <c' ed,(d1)
 >) → (<C,(d1:2,d2:1)>, <died,(d2:1)>, <came,(d1:1)>,
 <c' ed,(d1:1)>)

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Dynamic indexing

- Up to now, we have assumed that collections are static.
- They rarely are:
 - Documents come in over time and need to be inserted.
 - Documents are deleted and modified.
- This means that the dictionary and postings lists have to be modified:
 - Postings updates for terms already in dictionary
 - New terms added to dictionary

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Simplest approach

- Maintain "big" main index
- New docs go into "small" auxiliary index
- Search across both, merge results
- Deletions
 - Invalidation bit-vector for deleted docs
 - Filter docs output on a search result by this invalidation bit-vector
- Periodically, re-index into one main index

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Sec. 4.5

Issues with main and auxiliary indexes

- Problem of frequent merges you touch stuff a lot
- Poor performance during merge
- Actually:
 - Merging of the auxiliary index into the main index is efficient if we keep a separate file for each postings list.
 - Merge is the same as a simple append.
 - But then we would need a lot of files inefficient for OS.
- Assumption for the rest of the lecture: The index is one big file.
- In reality: Use a scheme somewhere in between (e.g., split very large postings lists, collect postings lists of length 1 in one file etc.)

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Sec. 4.

Logarithmic merge

- Maintain a series of indexes, each twice as large as the previous one
 - At any time, some of these powers of 2 are instantiated
- Keep smallest (Z₀) in memory
- Larger ones (I₀, I₁, ...) on disk
- If Z₀ gets too big (> n), write to disk as I₀
- or merge with I₀ (if I₀ already exists) as Z₁
- Either write merge Z₁ to disk as I₁ (if no I₁)
- Or merge with I₁ to form Z₂

```
LMERGEADDTOKEN(indexes, Z<sub>0</sub>, token)
  1 Z_0 \leftarrow \text{Merge}(Z_0, \{token\})
     if |Z_0| = n
  2
         then for i \leftarrow 0 to \infty
                do if I_i \in indexes
                       then Z_{i+1} \leftarrow \text{MERGE}(I_i, Z_i)
                               (Z_{i+1} \text{ is a temporary index on disk.})
                               indexes \leftarrow indexes - \{I_i\}
                        else I_i \leftarrow Z_i (Z_i becomes the permanent index I_i.)
  8
 9
                               indexes \leftarrow indexes \cup \{I_i\}
10
                               Break
11
                 Z_0 \leftarrow \emptyset
LogarithmicMerge()
1 Z_0 \leftarrow \emptyset (Z_0 is the in-memory index.)
2 indexes \leftarrow \emptyset
     while true
3
    do LMERGEADDTOKEN(indexes, Z<sub>0</sub>, GETNEXTTOKEN())
```

Logarithmic merge Auxiliary and main index: index construction time is O(T²) as each posting is touched in each merge. Logarithmic merge: Each posting is merged O(log T) times, so complexity is O(T log T) So logarithmic merge is much more efficient for index construction But query processing now requires the merging of O (log T) indexes Whereas it is O(1) if you just have a main and auxiliary index

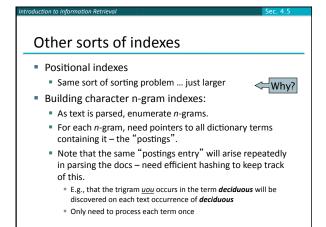
Further issues with multiple indexes

- Collection-wide statistics are hard to maintain
- E.g., when we spoke of spell-correction: which of several corrected alternatives do we present to the
 - We said, pick the one with the most hits
- How do we maintain the top ones with multiple indexes and invalidation bit vectors?
 - One possibility: ignore everything but the main index for such ordering
- Will see more such statistics used in results ranking

Dynamic indexing at search engines All the large search engines now do dynamic indexing

- Their indices have frequent incremental changes
 - News items, blogs, new topical web pages Sarah Palin. ..
- But (sometimes/typically) they also periodically reconstruct the index from scratch
 - Query processing is then switched to the new index, and the old index is deleted





Resources for today's lecture

- Chapter 4 of IIR
- MG Chapter 5
- Original publication on MapReduce: Dean and Ghemawat (2004)
- Original publication on SPIMI: Heinz and Zobel (2003)